# SMART Hydraulic Actuators (SHA)

Fusing the power of hydraulics with the precision of servo control.

ONICS

y Solutions I Actuation Techno

# **All-In-One Solution**

• Pre-Engineered, Factory setup & tested, ready to install

# **Precision Servo Control**

 Accurate control of position, force and speed

# **Energy Efficient - Small Footprint**

- Maximum force density; superior to electro-mechanical and pneumatic actuators
- Saves energy, power on demand
- Less heat, Less noise

# Eliminates the Hydraulic Infrastructure

- No hoses, no leaks
- Fewer components, significant cost savings

# **Reliable and Durable**

- No metal-to-metal wear points unlike roller or ball screw actuators
- Shock load resistant
- Exceptional long-life, minimal maintenance

The Smart Alternative to Hydraulic Cylinders and Ball Screw / Roller Screw Actuators



Innovation in Motion

kyntronics.com



# **Syntronics**

# SMART Hydraulic Actuators – System Features

# Why Choose the SMART Hydraulic Actuator?

The SHA combines the best features of hydraulic power with the precision of servo control (used in ball screw & roller screw electro-mechanical actuators), without the inherent disadvantages of those approaches. The result is an actuation solution with up to 170,000 LBs (755kN) of force and superior functionality at a lower price point.

- High-Precision Brushless Servo Motor
- Servo-Controlled, Precise Displacement, Bi-Directional Variable Speed Pump
- Manifold with Integral Valve Controls
- Heavy-Duty Rod / Cylinder with Patent-Pending Rod Compensation
- Servo Drive / Motion Controller
- Fieldbus Interface, IoT Compatible
- Pressure Sensor for Force Control Operation
- High-Resolution Position Sensor

# **Benefits of Kyntronics SHA** over Hydraulic Actuation and Ball Screw / Roller Screw Actuators



# Kyntronics SHA

- All-In-One, Factory Configured, ready to install
- Closed system, no leaks, minimal maintenance
- Energy efficient, only consumes power when operating
- Precision servo control of position, force, speed
- Quiet operation

# Kyntronics SHA

- Highest force density, small footprint
- Small cost increase as force /load requirements grow
- High efficiency, no metal-to-metal contact points improves reliability
- Tolerant of *"Shock Loads"*, high operational reliability
- Cannot be "back-driven"

# **Hydraulic Cylinder Actuators**

- Require an expensive HPU and many components that must be engineered,
- assembled and tested
  - Many connection points, hoses, prone to leaks
  - Runs continuously, significant energy consumption
  - Costly to precisely control
  - Very noisy
  - Requires regular HPU component maintenance and fluid changes



Replace this HPU mess with the SHA

## Ball Screw / Roller Screw Actuators

- Larger space requirements
- Expensive for high-force applications
- Gears and mechanical components create friction and losses
  - "Shock loads" can cause significant damage and premature localized wear. Require regular lubrication
  - Require a brake to hold position... additional expense



# **SHA Product Families**

### S-Series - General Purpose All-In-**One Replacement for Hydraulic Cylinders & Electro-Mechanical Actuators**

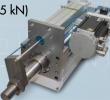
- Up to 85,000 lbf (377 kN)
- Up to 120" (3,048 mm) stroke length
- Up to 45 in/s
- (1, 159 mm/s)
- 115, 230, 460 VAC

### E-Series - High-Performance **Upgrade from Pneumatic & Electro-Mechanical Actuators**

- Up to 9,500 lbf (42 kN) • Up to 120" (3,048 mm) stroke length
- Up to 10.6 in/s (269 mm/s)
- 12, 24, 48 or 72 VDC
- IP68 option

### H-Series - High Speed / High Force In an Integrated Package

- Up to 170,000 lbf (775 kN)
- Up to 24" (610 mm)
- stroke length • Up to 45 in/s
- (1, 159 mm/s)
- 115, 230, 460 VAC



**Right-Angle** 

# SHA Configurations - Flexibility to fit your application



Temperature Monitoring

### **Control capabilities:**

- Position Control
  - Standard +/-0.010in (+/-0.250mm)
  - Precision +/-0.001in (+/-0.025mm)
- Force Control
- Position & Force Control
- Four Quadrant Motion Control
- Compound Moves / Multi-axis Synchronization

### **Control Feedback Options:**

- Force
  - Pressure Transducer(s) and/or Load Cell; 0-10Vdc or 0-20mA
- Position
- Internal or External Mount
- Analog: 0-10Vdc or 0-20mA
- Digital: SSI, TTL A Quad B, Profinet, EtherNet/IP, CANopen, IO-Link

Ethernet/IP

Other - Consult Factory

EtherCAT

- As low as 4.0µin (0.1 µm) resolution

### **Networking:**

- Modbus RT
- Modbus TCP
- PROFIBUS
- PROFINET







Threaded Male SI



Threaded Female Standard Threaded Male SI













Clevis, 0 Degrees Clevis, 90 Degrees (O Degrees Position Shown)



End Feet

Rear Flange Plate

Rod Eye Bracket, O Degrees Rod Eye Bracket, 90 Degrees (O Degrees Position Shown)



Front Flange Plate

Side Feet









# Kyntronics SMART Hydraulic Actuators are used successfully in many industries and applications.



- Aerospace
- Automotive Defense / Military
- Entertainment / Animatronics
- Energy

Forestry /Lumber

- Special Machines/Industrial Machinery
- Bending Metal Fabrication
- Closing and Clamping
- Door / Hatch Actuation
- Flexible Tooling
- Folding
- Handling Lifting
- Moving & Motion Simulation
- Positioning
- Pressing
- Punching
- Testing /Inspection Welding
- S-Series SMART Hydraulic Actuator Product Specifications

		Continuous Duty @ 230Vac		Peak @ 230Vac			Continuous Duty @ 230Vac		Peak @ 230Vac	
	*SHA Series	Force-Lbf (kN)	Avg-In/s (mm/s)	Force-Lbf (kN)	Avg-In/s (mm/s)	Series	Force-Lbf (kN)	Avg-In/s (mm/s)	Force-Lbf (kN)	Avg-In/s (mm/s)
	S08C10-13	966 (4.3)	8.8 (39.4)	2,356 (10.5)	8.8 (39.4)	S08C32-13	10,208 (45.4)	0.7 (3.1)	24,887 (110.7)	0.7 (3.1)
To Maximize Speed	S13C10-36	748 (3.3)	45.6 (202.9)	2,239 (10.0)	53.2 (236.7)	S13C32-36	7,903 (35.2)	3.6 (16.1)	23,652 (105.2)	4.2 (18.8)
	S19C10-36	1,789 (8.0)	45.6 (202.9)	2,239 (10.0)	53.2 (236.7)	S19C32-36	18,900 (84.1)	3.6 (16.1)	23,652 (105.2)	4.2 (18.8)
	S08C15-13	2,174 (9.7)	4.2 (18.5)	5,301 (23.6)	4.2 (18.5)	S08C40-13	15,463 (68.8)	0.5 (2.2)	37,699 (167.7)	0.5 (2.2)
	S13C15-36	1,683 (7.5)	21.5 (95.6)	5,038 (22.4)	25.1 (111.5)	S13C40-36	11,971 (53.2)	2.5 (11.2)	35,828 (159.4)	2.9 (13.1)
	S19C15-36	4,026 (17.9)	21.5 (95.6)	5,038 (22.4)	25.1 (111.5)	S19C40-36	28,629 (127.3)	2.5 (11.2)	35,828 (159.4)	2.9 (13.1)
	S08C20-13	3,866 (17.2)	2.0 (8.7)	9,425 (41.9)	2.0 (8.7)	S08C50-13	24,160 (107.5)	0.3 (1.5)	58,905 (262.0)	0.3 (1.5)
	S13C20-36	2,993 (13.3)	10.1 (44.8)	8,957 (39.8)	11.8 (52.3)	S13C50-36	18,704 (83.2)	1.8 (7.9)	55,982 (249.0)	2.1 (9.2)
	S19C20-36	7,157 (31.8)	10.1 (44.8)	8,957 (39.8)	11.8 (52.3)	S19C50-36	44,733 (199.0)	1.8 (7.9)	55,982 (249.0)	2.1 (9.2)
	S08C25-13	6,040 (26.9)	1.3 (5.8)	14,726 (65.5)	1.3 (5.8)	S08C60-13	34,791 (154.8)	0.2 (1.0)	84,823 (377.3)	0.2 (1.0)
	S13C25-36	4,676 (20.8)	6.7 (29.9)	13,995 (62.3)	7.8 (34.9)	S13C60-36	26,934 (119.8)	1.2 (5.4)	80,614 (358.6)	1.4 (6.3)
	S19C25-36	11,183 (49.7)	6.7 (29.9)	13,995 (62.3)	7.8 (34.9)	S19C60-36	64,416 (286.5)	1.2 (5.4)	80,614 (358.6)	1.4 (6.3)
	<u>AE EINMONETIVE AND BESEONSIVE FIMMOVEDVEEMMU HESKUNSIVE D</u>									
To Maximize Force	S08C10-05	2,356 (10.5)	2.2 (9.8)	2,356 (10.5)	2.2 (9.8)	S08C32-05	24,887 (110.7)	0.2 (0.8)	24,887 (110.7)	0.2 (0.8)
	S13C10-23	2,310 (10.3)	14.8 (65.7)	2,356 (10.5)	17.2 (76.7)	S13C32-23	24,399 (108.5)	1.2 (5.2)	24,887 (110.7)	1.4 (6.1)
	S19C10-34	2,266 (10.1)	36.0 (160.2)	2,356 (10.5)	42.0 (186.9)	S19C32-34	23,940 (106.5)	2.9 (12.7)	24,887 (110.7)	3.3 (14.9)
	S08C15-05	5,301 (23.6)	1.0 (4.6)	5,301 (23.6)	1.0 (4.6)	S08C40-05	37,699 (167.7)	0.1 (0.5)	37,699 (167.7)	0.1 (0.5)
	S13C15-23	5,197 (23.1)	7.0 (31.0)	5,301 (23.6)	8.1 (36.1)	S13C40-23	36,960 (164.4)	0.8 (3.6)	37,699 (167.7)	1.0 (4.2)
	S19C15-34	5,100 (22.7)	17.0 (75.5)	5,301 (23.6)	19.8 (88.1)	S19C40-34	36,264 (161.3)	2.0 (8.8)	37,699 (167.7)	2.3 (10.3)
	S08C20-05	9,425 (41.9)	0.5 (2.2)	9,425 (41.9)	0.5 (2.2)	S08C50-05	58,905 (262.0)	0.1 (0.4)	58,905 (262.0)	0.1 (0.4)
	S13C20-23	9,240 (41.1)	3.3 (14.5)	9,425 (41.9)	3.8 (16.9)	S13C50-23	57,749 (256.9)	0.6 (2.6)	58,905 (262.0)	0.7 (3.0)
	S19C20-34	9,066 (40.3)	8.0 (35.4)	9,425 (41.9)	9.3 (41.3)	S19C50-34	56,662 (252.0)	1.4 (6.2)	58,905 (262.0)	1.6 (7.3)
	S08C25-05	14,726 (65.5)	0.3 (1.4)	14,726 (65.5)	0.3 (1.4)	S08C60-05	84,823 (377.3)	0.1 (0.3)	84,823 (377.3)	0.1 (0.3)
	S13C25-23	14,437 (64.2)	2.2 (9.7)	14,726 (65.5)	2.5 (11.3)	S13C60-23	83,159 (369.9)	0.4 (1.7)	84,823 (377.3)	0.5 (2.0)
	S19C25-34	14,166 (63.0)	5.3 (23.6)	14,726 (65.5)	6.2 (27.6)	S19C60-34	81,593 (362.9)	1.0 (4.2)	84,823 (377.3)	1.1 (4.9)

\* Shown configurations are a sampling of many options that are available. Contact Kyntronics for a specific configuration for your application. Refer to Kyntronics.com for E and H-Series Product Specifications.

# **About Kyntronics**

An ISO 9001; 2015, AS9100D certified company, all Kyntronics actuation products are made in the USA. With vast experience in industrial, aerospace and medical industries, our in-house team of mechanical, electronics, hydraulic and software engineers have hundreds of years of engineering experience. Customer-centric, we thrive on 'solving the unsolvable' application problems while working with customers worldwide.

To discuss your application and see how the SMART Hydraulic Actuator can maximize cost efficiencies, contact Kyntronics today!



### Innovation in Motion

6565 Davis Industrial Parkway Solon, OH 44139 PH: 440.220.5990 FX: 866.854.4578 Toll Free (US only): 855.596.8765 kyntronics.com

## Medical Equipment Metals / Metal Fabrication

 Mobile Equipment Plastics